- In many applications, a discrete-time signal x[n] is split into a number of subband signals {v_k[n]} by means of an analysis filter bank
- The subband signals are then processed
- Finally, the processed subband signals are combined by a synthesis filter bank resulting in an output signal *y*[*n*]

1

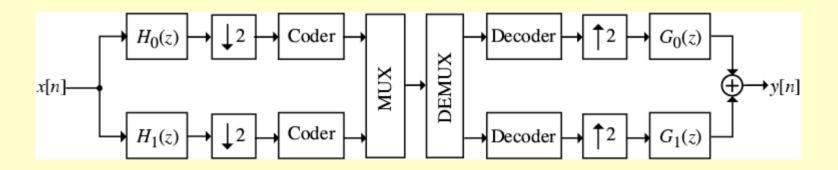
- If the subband signals {v_k[n]} are bandlimited to frequency ranges much smaller than that of the original input signal x[n], they can bedown-sampled before processing
- Because of the lower sampling rate, the processing of the down-sampled signals can be carried out more efficiently

- After processing, these signals are then upsampled before being combined by the synthesis filter bank into a higher-rate signal
- The combined structure is called a quadrature-mirror filter (QMF) bank

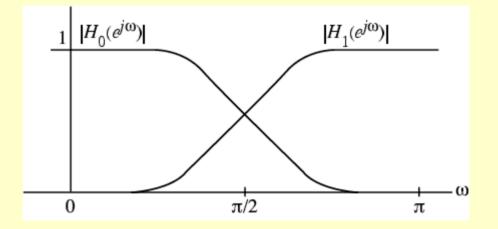
If the down-sampling and up-sampling factors are equal to or greater than the number of bands of the filter bank, then the output y[n] can be made to retain some or all of the characteristics of the input signal x[n] by choosing appropriately the filters in the structure

- If the up-sampling and down-sampling factors are equal to the number of bands, then the structure is called a critically sampled filter bank
- The most common application of this scheme is in the efficient coding of a signal x[n]

 Figure below shows the basic two-channel QMF bank-based subband codec (coder/decoder)



• The analysis filters $H_0(z)$ and $H_1(z)$ have typically a lowpass and highpass frequency responses, respectively, with a cutoff at $\pi/2$



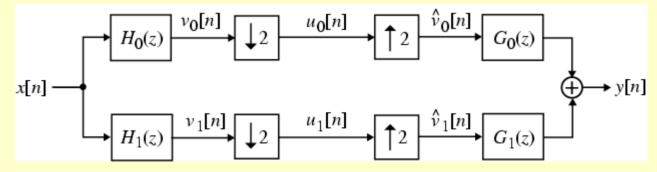
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- Each down-sampled subband signal is encoded by exploiting the special spectral properties of the signal, such as energy levels and perceptual importance
- It follows from the figure that the sampling rates of the output y[n] and the input x[n] are the same

- The analysis and the synthesis filters are chosen so as to ensure that the reconstructed output y[n] is a reasonably close replica of the input x[n]
- Moreover, they are also designed to provide good frequency selectivity in order to ensure that the sum of the power of the subband signals is reasonably close to the input signal power

- In practice, various errors are generated in this scheme
- In addition to the coding error and errors caused by transmission of the coded signals through the channel, the QMF bank itself introduces several errors due to the sampling rate alterations and imperfect filters
- We ignore the coding and the channel errors

- We investigate only the errors caused by the sampling rate alterations and their effects on the performance of the system
- To this end, we consider the QMF bank structure without the coders and the decoders as shown below



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• Making use of the input-output relations of the down-sampler and the up-sampler in the *z*-domain we arrive at

$$V_k(z) = H_k(z)X(z),$$

$$U_k(z) = \frac{1}{2} \{ V_k(z^{1/2}) + V_k(-z^{1/2}) \}, \quad k = 0, 1$$

$$\hat{V}_k(z) = U_k(z^2)$$

• From the first and the last equations we obtain after some algebra

$$\hat{V}_{k}(z) = \frac{1}{2} \{ V_{k}(z) + V_{k}(-z) \}$$
$$= \frac{1}{2} \{ H_{k}(z) X(z) + H_{k}(-z) X(-z) \}$$

• The reconstructed output of the filter bank is given by $Y(z) = G_0(z)\hat{V}_0(z) + G_1(z)\hat{V}_1(z)$

• From the two equations of the previous slide we arrive at

$$Y(z) = \frac{1}{2} \{H_0(z)G_0(z) + H_1(z)G_1(z)\}X(z) + \frac{1}{2} \{H_0(-z)G_0(z) + H_1(-z)G_1(z)\}X(-z)\}$$

• The second term in the above equation is due to the aliasing caused by sampling rate alteration

• The input-output equation of the filter bank can be compactly written as

Y(z) = T(z)X(z) + A(z)X(-z)

where T(z), called the distortion transfer function, is given by

$$T(z) = \frac{1}{2} \{ H_0(z) G_0(z) + H_1(z) G_1(z) \}$$

and

$$A(z) = \frac{1}{2} \{ H_0(-z)G_0(z) + H_1(-z)G_1(z) \}$$

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- Since the up-sampler and the down-sampler are linear time-varying components, in general, the 2-channel QMF structure is a linear time-varying system
- It can be shown that the 2-channel QMF structure has a period of 2
- However, it is possible to choose the analysis and synthesis filters such that the aliasing effect is canceled resulting in a time-invariant operation

• To cancel aliasing we need to ensure that A(z) = 0, i.e.,

 $H_0(-z)G_0(z) + H_1(-z)G_1(z) = 0$

• For aliasing cancellation we can choose

$$\frac{G_0(z)}{G_1(z)} = -\frac{H_1(-z)}{H_0(-z)}$$

• This yields

 $G_0(z) = C(z)H_1(-z), \quad G_1(z) = -C(z)H_0(-z),$ where C(z) is an arbitrary rational function

• If the above relations hold, then the QMF system is time-invariant with an inputoutput relation given by Y(z) = T(z)X(z)

where

$$T(z) = \frac{1}{2} \{ H_0(z) H_1(-z) + H_1(z) H_0(-z) \}$$

• On the unit circle, we have $Y(e^{j\omega}) = T(e^{j\omega})X(e^{j\omega}) = |T(e^{j\omega})| e^{j\phi(\omega)}X(e^{j\omega})$

• If T(z) is an allpass function, i.e., $|T(e^{j\omega})| = d$ with $d \neq 0$ then

$$|Y(e^{j\omega})| = d |X(e^{j\omega})|$$

indicating that the output of the QMF bank has the same magnitude response as that of the input (scaled by *d*) but exhibits phase distortion

• The filter bank is said to be magnitude preserving

• If T(z) has linear phase, i.e.,

$$\arg\{T(e^{j\omega})\} = \phi(\omega) = \alpha\omega + \beta$$

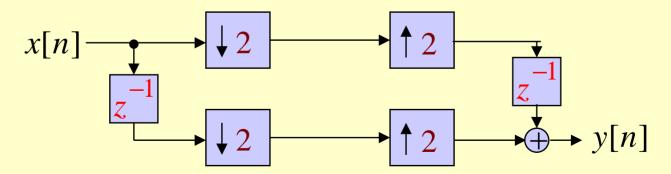
then

$$\arg\{Y(e^{j\omega})\} = \arg\{X(e^{j\omega})\} + \alpha\omega + \beta$$

• The filter bank is said to be phasepreserving but exhibits magnitude distortion

- If an alias-free filter bank has no magnitude and phase distortion, then it is called a perfect reconstruction (PR) QMF bank
- In such a case, $T(z) = dz^{-\ell}$ resulting in $Y(z) = dz^{-\ell} X(z)$
- In the time-domain, the input-output relation for all possible inputs is given by $y[n] = d x[n - \ell]$

- Thus, for a perfect reconstruction QMF bank, the output is a scaled, delayed replica of the input
- Example Consider the system shown below



• Comparing this structure with the general QMF bank structure we conclude that here we have

$$H_0(z) = 1$$
, $H_1(z) = z^{-1}$, $G_0(z) = z^{-1}$, $G_1(z) = 1$

• Substituting these values in the expressions for *T*(*z*) and *A*(*z*) we get

$$T(z) = \frac{1}{2}(z^{-1} + z^{-1}) = z^{-1}$$
$$A(z) = \frac{1}{2}(z^{-1} - z^{-1}) = 0$$

- Thus the simple multirate structure is an alias-free perfect reconstruction filter bank
- However, the filters in the bank do not provide any frequency selectivity

• A very simple alias-free 2-channel QMF bank is obtained when

 $H_1(z) = H_0(-z)$

• The above condition, in the case of a real coefficient filter, implies

$$|H_1(e^{j\omega})| = |H_0(e^{j(\pi-\omega)})|$$

indicating that if $H_0(z)$ is a lowpass filter, then $H_1(z)$ is a highpass filter, and vice versa

- The relation $|H_1(e^{j\omega})| = |H_0(e^{j(\pi-\omega)})|$ indicates that $|H_1(e^{j\omega})|$ is a mirror-image of $|H_0(e^{j\omega})|$ with respect to $\pi/2$, the quadrature frequency
- This has given rise to the name quadraturemirror filter bank

- Substituting $H_1(z) = H_0(-z)$ in $G_0(z) = C(z)H_1(-z), \quad G_1(z) = -C(z)H_0(-z),$ with C(z) = 1 we get $G_0(z) = H_1(-z), \quad G_1(z) = -H_1(z) = -H_0(-z)$
- The above equations imply that the two analysis filters and the two synthesis filters are essentially determined from one transfer function $H_0(z)$

- Moreover, if $H_0(z)$ is a lowpass filter, then $G_0(z)$ is also a lowpass filter and $G_1(z)$ is a highpass filter
- The distortion function in this case reduces to $T(z) = \frac{1}{2} \{ H_0^2(z) - H_1^2(z) \} = \frac{1}{2} \{ H_0^2(z) - H_0^2(-z) \}$

- A computationally efficient realization of the above QMF bank is obtained by realizing the analysis and synthesis filters in polyphase form
- Let the 2-band Type 1 polyphase representation of $H_0(z)$ be given by $H_0(z) = E_0(z^2) + z^{-1}E_1(z^2)$

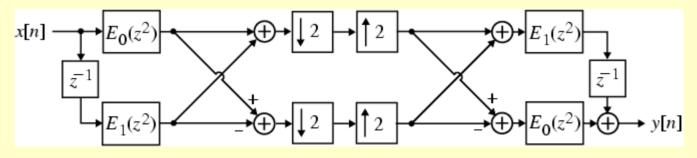
• Then from the relation $H_1(z) = H_0(-z)$ it follows that

$$H_1(z) = E_0(z^2) - z^{-1}E_1(z^2)$$

• Combining the last two equations in a matrix form we get

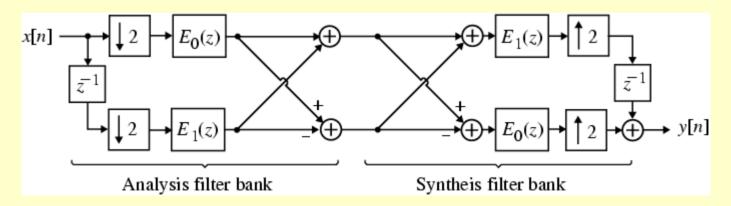
$$\begin{bmatrix} H_0(z) \\ H_0(z) \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} E_0(z^2) \\ z^{-1}E_1(z^2) \end{bmatrix}$$

- Likewise, the synthesis filters can be expressed in a matrix form as $\begin{bmatrix}G_0(z) & G_1(z)\end{bmatrix} = \begin{bmatrix}z^{-1}E_1(z^2) & E_0(z^2)\end{bmatrix} \begin{bmatrix}1 & 1\\ 1 & -1\end{bmatrix}$ Making use of the last two equations we can
- Making use of the last two equations we can redraw the two-channel QMF bank as shown below



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• Making use of the cascade equivalences, the above structure can be further simplified as shown below



• Substituting the polyphase representations of the analysis filters we arrive at the expression for the distortion function T(z) in terms of the polyphase components as $T(z) = 2z^{-1}E_0(z^2)E_1(z^2)$

- Example Let $H_0(z) = 1 + z^{-1}$
- Its polyphase components are $E_0(z^2) = 1, \quad E_1(z^2) = 1$
- Hence

$$H_1(z) = H_0(-z) = E_0(z^2) - z^{-1}E_1(z^2) = 1 - z^{-1}$$

• Likewise

$$G_0(z) = z^{-1}E_1(z^2) + E_0(z^2) = 1 + z^{-1}$$

$$G_1(z) = z^{-1}E_1(z^2) - E_0(z^2) = -1 + z^{-1}$$

• The distortion transfer function for this realization is thus given by

$$T(z) = 2z^{-1}E_0(z^2)E_1(z^2) = 2z^{-1}$$

• The resulting structure is a perfect reconstruction QMF bank

Alias-Free FIR QMF Bank

- If in the above alias-free QMF bank $H_0(z)$ is a linear-phase FIR filter, then its polyphase components $E_0(z)$ and $E_1(z)$, are also linear-phase FIR transfer functions
- In this case, $T(z) = 2z^{-1}E_0(z^2)E_1(z^2)$ exhibits a linear-phase characteristic
- As a result, the corresponding 2-channel QMF bank has no phase distortion

- However, in general $|T(e^{j\omega})|$ is not a constant, and as a result, the QMF bank exhibits magnitude distortion
- We next outline a method to minimize the residual amplitude distortion
- Let $H_0(z)$ be a length-*N* real-coefficient linear-phase FIR transfer function:

$$H_0(z) = \sum_{n=0}^{N-1} h_0[n] z^{-n}$$

- Note: H₀(z) can either be a Type 1 or a Type 2 linear-phase FIR transfer function since it has to be a lowpass filter
- Then $h_0[n]$ satisfy the condition $h_0[n] = h_0[N-n]$
- In this case we can write $H_0(e^{j\omega}) = e^{j\omega N/2} \tilde{H}_0(\omega)$
- In the above $\tilde{H}_0(\omega)$ is the amplitude function, a real function of ω

• The frequency response of the distortion transfer function can now be written as

$$T(e^{j\omega}) = \frac{e^{-jN\omega}}{2} \{ |H_0(e^{j\omega})|^2 - (-1)^N |H_0(e^{j(\pi-\omega)})|^2 \}$$

• From the above, it can be seen that if *N* is even, then $T(e^{j\omega}) = 0$ at $\omega = \pi/2$, implying severe amplitude distortion at the output of the filter bank

- $\implies N \text{ must be odd, in which case we have}$ $T(e^{j\omega}) = \frac{e^{-jN\omega}}{2} \{ |H_0(e^{j\omega})|^2 + |H_0(e^{j(\pi-\omega)})|^2 \}$ $= \frac{e^{-jN\omega}}{2} \{ |H_0(e^{j\omega})|^2 + |H_1(e^{j\omega})|^2 \}$
- It follows from the above that the FIR 2channel QMF bank will be of perfect reconstruction type if $|H_0(e^{j\omega})|^2 + |H_1(e^{j\omega})|^2 = 1$

- Now, the 2-channel QMF bank with linearphase filters has no phase distortion, but will always exhibit amplitude distortion unless $|T(e^{j\omega})|$ is a constant for all ω
- If $H_0(z)$ is a very good lowpass filter with $|H_0(e^{j\omega})| \cong 1$ in the passband and $|H_0(e^{j\omega})| \cong 0$ in the stopband, then $H_1(z)$ is a very good highpass filter with its passband coinciding with the stopband of $H_0(z)$, and vice-versa

- As a result, $|T(e^{j\omega})| \cong 1/2$ in the passbands of $H_0(z)$ and $H_1(z)$
- Amplitude distortion occurs primarily in the transition band of these filters
- Degree of distortion determined by the amount of overlap between their squared-magnitude responses

- This distortion can be minimized by controlling the overlap, which in turn can be controlled by appropriately choosing the passband edge of $H_0(z)$
- One way to minimize the amplitude distortion is to iteratively adjust the filter coefficients h₀[n] of H₀(z) on a computer such that

$$|H_0(e^{j\omega})|^2 + |H_1(e^{j\omega})|^2 \cong 1$$

 $_{43}$ is satisfied for all values of ω

- To this end, the objective function φ to be minimized can be chosen as a linear combination of two functions:
 - (1) stopband attenuation of $H_0(z)$, and
 - (2) sum of squared magnitude responses of $H_0(z)$ and $H_1(z)$

• One such objective function is given by

$$\phi = \alpha \phi_1 + (1 - \alpha) \phi_2$$

where

$$\phi_1 = \int_{\omega_s}^{\pi} \left| H(e^{j\omega}) \right|^2 d\omega$$

and

$$\phi_2 = \int_0^{\pi} \left(1 - \left| H_0(e^{j\omega}) \right|^2 - \left| H_1(e^{j\omega}) \right|^2 \right)^2 d\omega$$

and $0 < \alpha < 1$, and $\omega_s = \frac{\pi}{2} + \varepsilon$ for some small $\varepsilon > 0$

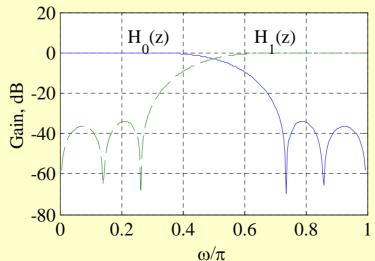
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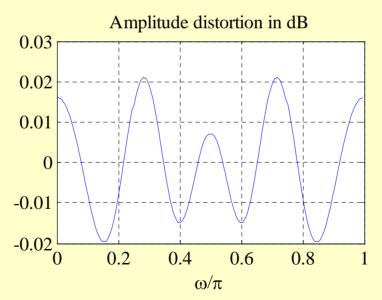
- Since $|T(e^{j\omega})|$ is symmetric with respect to $\pi/2$, the second integral in the objective function ϕ can be replaced with $\phi_2 = 2 \int_{0}^{\pi/2} \left(1 \left| H_0(e^{j\omega}) \right|^2 \left| H_1(e^{j\omega}) \right|^2 \right)^2 d\omega$
- After ϕ has been made very small by the optimization procedure, both ϕ_1 and ϕ_2 will also be very small

- Using this approach, Johnston has designed a large class of linear-phase FIR filters meeting a variety of specifications and has tabulated their impulse response coefficients
- Program 10_9 can be used to verify the performance of Johnston's filters

• <u>Example</u> - The gain responses of the length-12 linear-phase FIR lowpass filter 12B and its power-complementary highpass filter obtained using Program 10_9 are shown below



• The program then computes the amplitude distortion $|H_0(e^{j\omega})|^2 + |H_1(e^{j\omega})|^2$ in dB as shown below



- From the gain response plot it can be seen that the stopband edge ω_s of the lowpass filter12B is about 0.71π , which corresponds to a transition bandwidth of $(\omega_s - 0.5\pi)/2 = 0.105\pi$
- The minimum stopband attenuation is approximately 34 dB

• The amplitude distortion function is very close to 0 dB in both the passbands and the stopbands of the two filters, with a peak value of ± 0.02 dB

• Under the alias-free conditions of

 $G_0(z) = H_1(-z),$ $G_1(z) = -H_0(-z)$ and the relation $H_1(z) = H_0(-z)$, the distortion function T(z) is given by

$$T(z) = 2z^{-1}E_0(z^2)E_1(z^2)$$

• If *T*(*z*) is an allpass function, then its magnitude response is a constant, and as a result its corresponding QMF bank has no magnitude distortion

• Let the polyphase components $E_0(z)$ and $E_1(z)$ of $H_0(z)$ be expressed as $E_0(z) = \frac{1}{2}\mathcal{A}_0(z), \quad E_1(z) = \frac{1}{2}\mathcal{A}_1(z)$ with $\mathcal{A}_0(z)$ and $\mathcal{A}_1(z)$ being stable allpass functions

• Thus,
$$H_0(z) = \frac{1}{2} \Big[\mathcal{A}_0(z^2) + z^{-1} \mathcal{A}_1(z^2) \Big]$$

 $H_1(z) = \frac{1}{2} \Big[\mathcal{A}_0(z^2) - z^{-1} \mathcal{A}_1(z^2) \Big]$

• In matrix form, the analysis filters can be expressed as

$$\begin{bmatrix} H_0(z) \\ H_0(z) \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} \mathcal{A}_0(z^2) \\ z^{-1} \mathcal{A}_1(z^2) \end{bmatrix}$$

• The corresponding synthesis filters in matrix form are given by

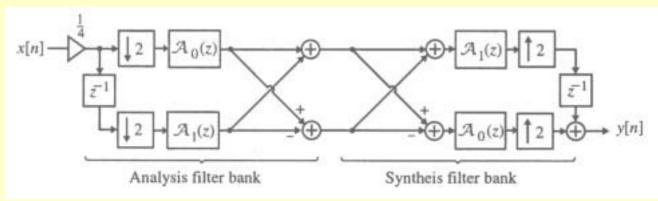
$$\begin{bmatrix} G_0(z) & G_1(z) \end{bmatrix} = \frac{1}{2} \begin{bmatrix} z^{-1} \mathcal{A}_1(z^2) & \mathcal{A}_0(z^2) \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

• Thus, the synthesis filters are given by

$$G_0(z) = \frac{1}{2} [\mathcal{A}_0(z^2) + z^{-1} \mathcal{A}_1(z^2)] = H_0(z)$$

$$G_1(z) = \frac{1}{2} [-\mathcal{A}_0(z^2) + z^{-1} \mathcal{A}_1(z^2)] = -H_1(z)$$

• The realization of the magnitude-preserving 2-channel QMF bank is shown below



• From $H_0(z) = \frac{1}{2} \left[\mathcal{A}_0(z^2) + z^{-1} \mathcal{A}_1(z^2) \right]$ it can be seen that the lowpass transfer function $H_0(z)$ has a polyphase-like decomposition, except here the polyphase components are stable allpass transfer functions

• It has been shown earlier that a boundedreal (BR) transfer function $H_0(z) = P_0(z)/D(z)$ of odd order, with no common factors between its numerator and denominator, can be expressed in the form $H_0(z) = \frac{1}{2} \Big[\mathcal{A}_0(z^2) + z^{-1} \mathcal{A}_1(z^2) \Big]$

if it satisfies the power-symmetry condition $H_0(z)H_0(z^{-1}) + H_0(-z)H_0(-z^{-1}) = 1$

and has a symmetric numerator $P_0(z)$

• It has also been shown that any odd-order elliptic lowpass half-band filter $H_0(z)$ with a frequency response specification given by $1-\delta < |H(e^{j\omega})| < 1$ for $0 < \omega < \omega$

$$|\mathcal{S}_p \leq |H(e^s)| \leq 1$$
, for $0 \leq \omega \leq \omega_p$
 $|H(e^{j\omega})| \leq \delta_s$, for $\omega_s \leq \omega \leq \pi$

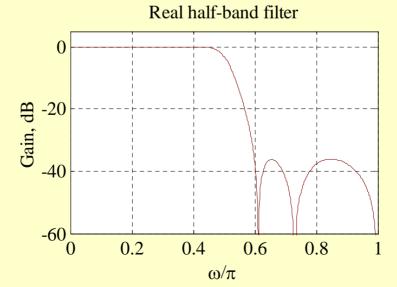
and satisfying the conditions $\omega_p + \omega_s = \pi$ and $\delta_s^2 = 4\delta_p (1 - \delta_p)$ can always be expressed in the form

$$H_0(z) = \frac{1}{2} \Big[\mathcal{A}_0(z^2) + z^{-1} \mathcal{A}_1(z^2) \Big]$$

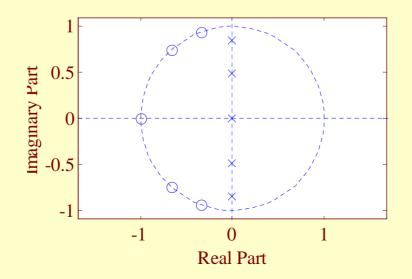
- The poles of the elliptic filter satisfying the two conditions on bandedges and ripples lie on the imaginary axis
- Using the pole-interlacing property discussed earlier, on can readily identify the expressions for the two allpass transfer functions $\mathcal{A}_0(z)$ and $\mathcal{A}_1(z)$

- Example The frequency response specifications of a real-coefficient lowpass half-band filter are given by: $\omega_p = 0.4\pi$, $\omega_s = 0.6\pi$, and $\delta_s = 0.0155$
- From $\delta_s^2 = 4\delta_p (1 \delta_p)$ we get $\delta_p = 0.00012013$
- In dB, the passband and stopband ripples are Rp = 0.0010435178 and Rs = 36.193366

- Using the M-file ellipord we determine the minimum order of the elliptic lowpass filter to be 5
- Next, using the M-file ellip the transfer function of the lowpass filter is determined whose gain response is shown below



- The poles obtained using the function tf2zp are at z = 0, $z = \pm j0.486625263$, and $z = \pm j0.486625263$
- The pole-zero plot obtained using zplane is shown below



• Using the pole-interlacing property we arrive at the transfer functions of the two allpass filters as given below:

$$\mathcal{A}_0(z^2) = \frac{z^{-2} + 0.2368041466}{1 + 0.2368041466z^{-2}}$$

$$\mathcal{A}_1(z^2) = \frac{z^2 + 0.7149039978}{1 + 0.7149039978z^{-2}}$$