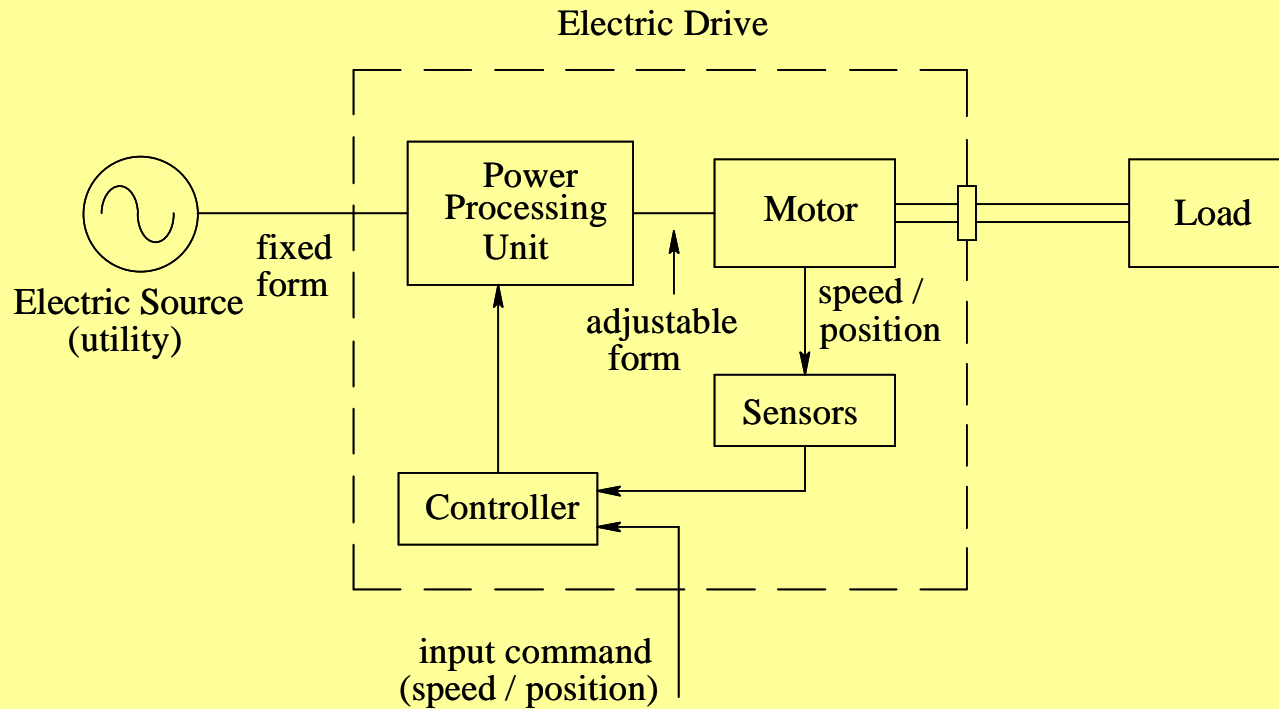


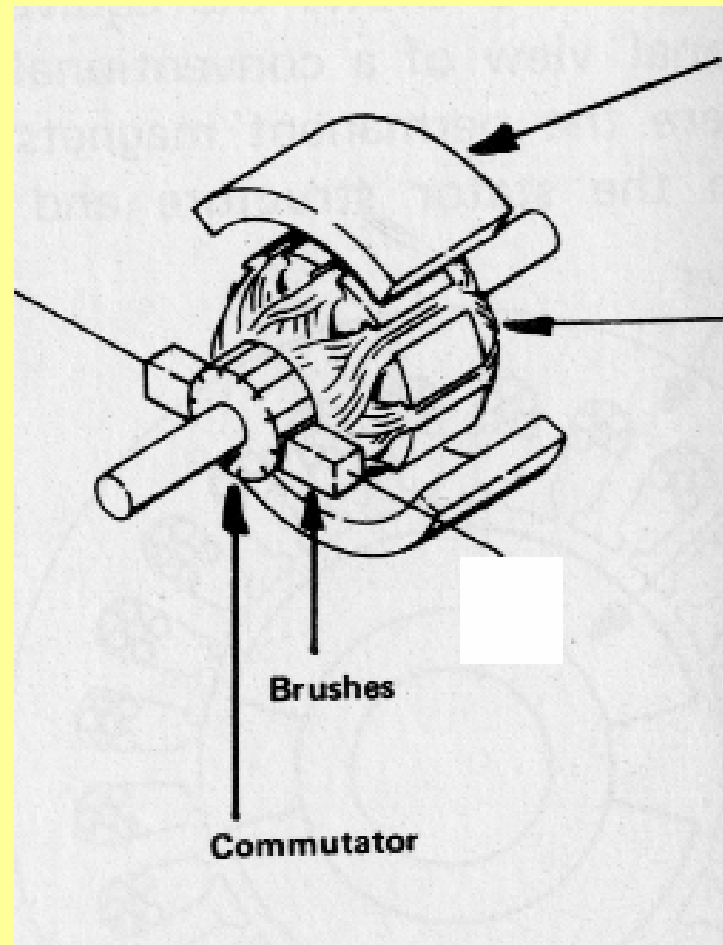
# Converter Ratings in Various Applications

- Voltage and Current Ratings in Converters in:
  - Electric Drives
  - UPS
  - Power Systems

# Adjustable-Speed Drive:



# DC MOTORS



stator  
magnets

rotor  
winding

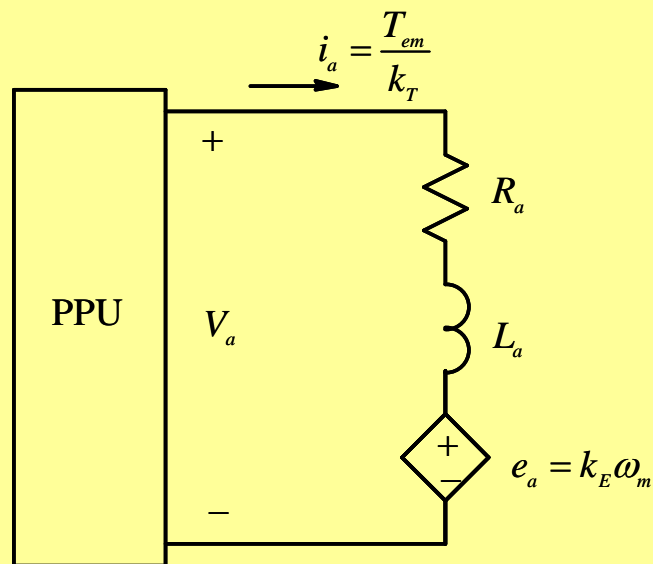
Brushes

Commutator

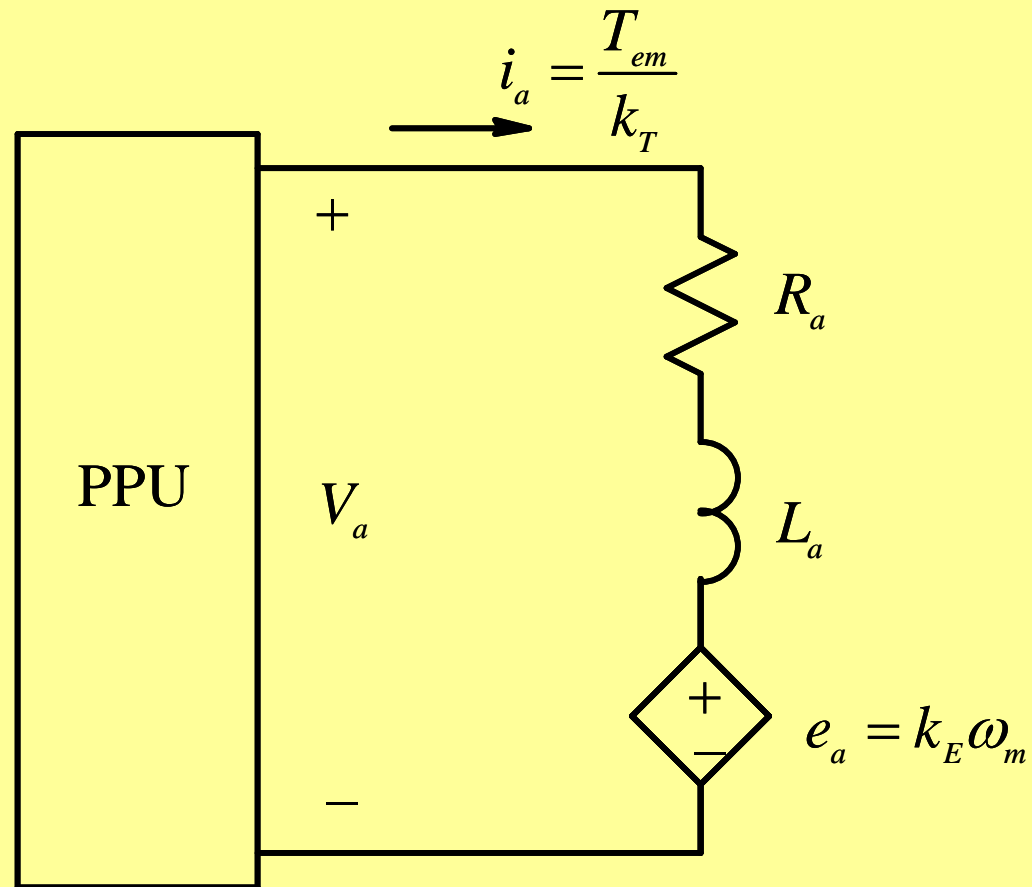
## DC-Machine Equivalent Circuit

$$v_a = e_a + R_a i_a + L_a \frac{di_a}{dt}$$

$$\frac{d\omega_m}{dt} = \frac{1}{J_{eq}} (T_{em} - T_L)$$



# Operating Principles of DC Machines

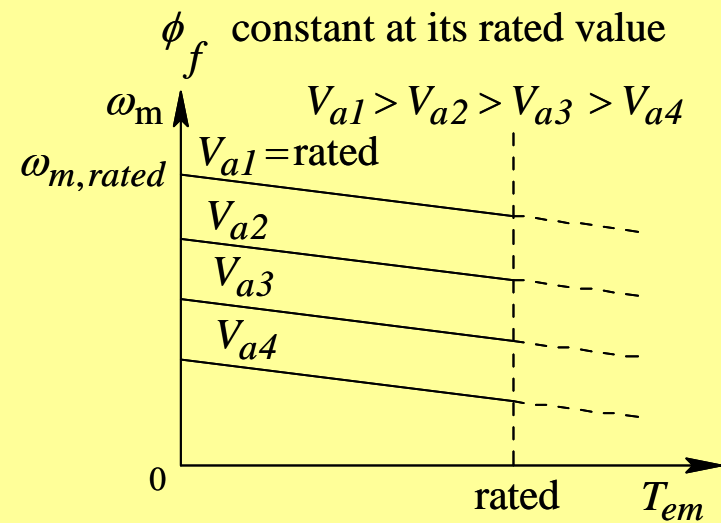
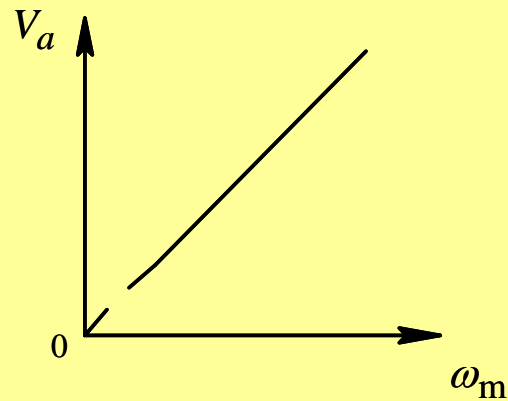


$$k_T = k_E$$

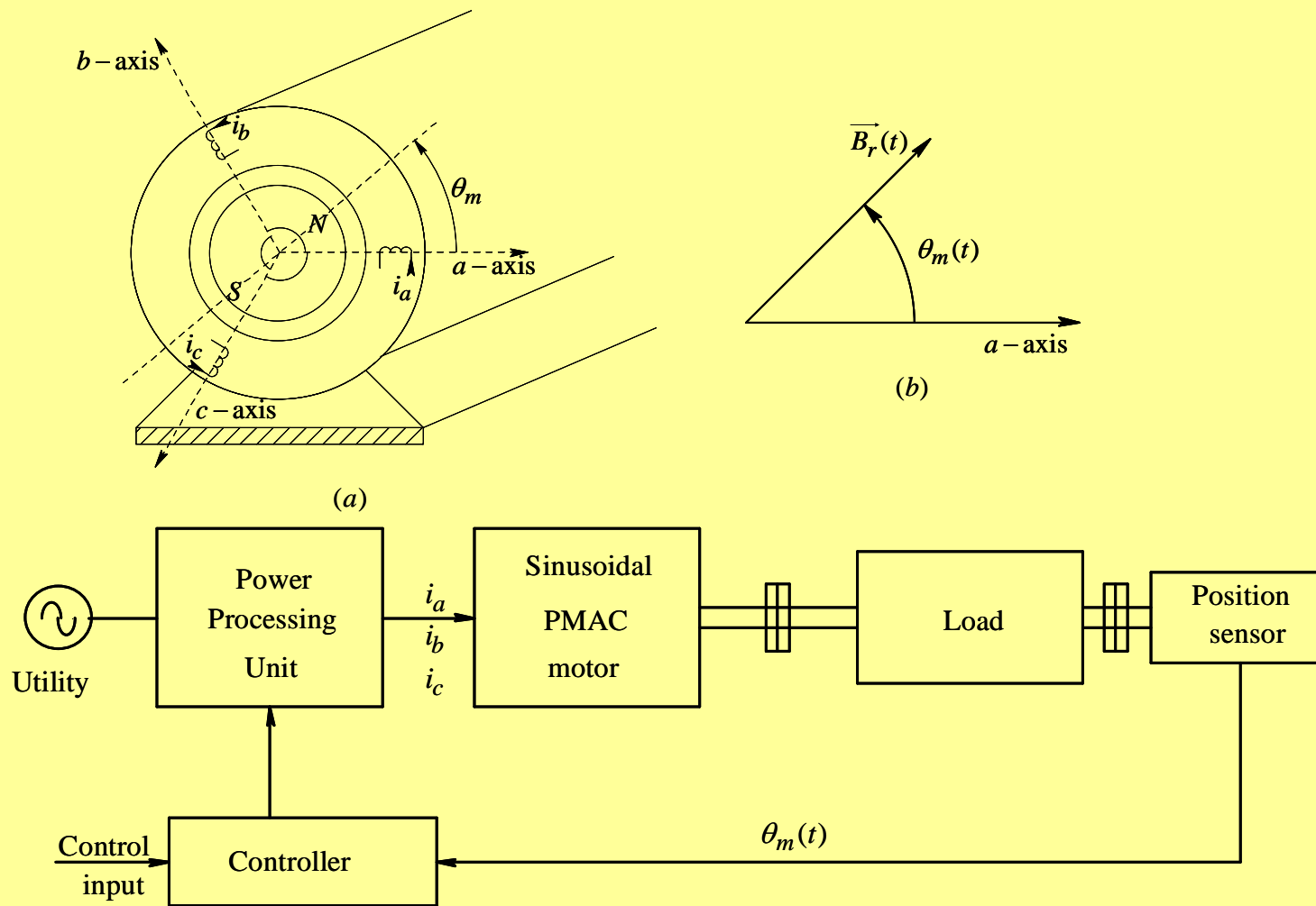
## Torque-Speed Characteristics

$$V_a = k_E \omega_m + R_a I_a$$

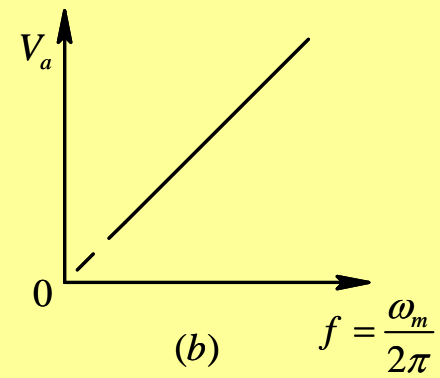
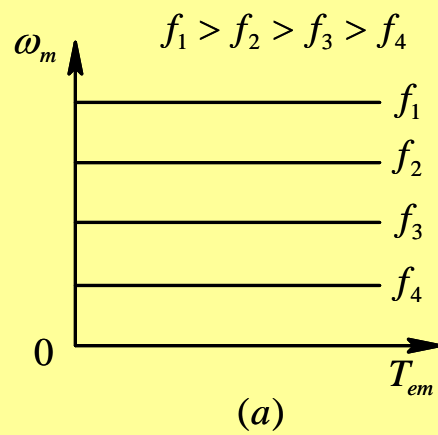
$$I_a = \frac{T_{em} (= T_L)}{k_T}$$



# PERMANENT-MAGNET AC MACHINES

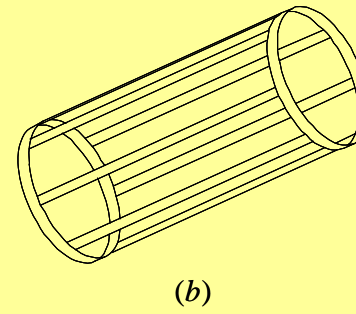
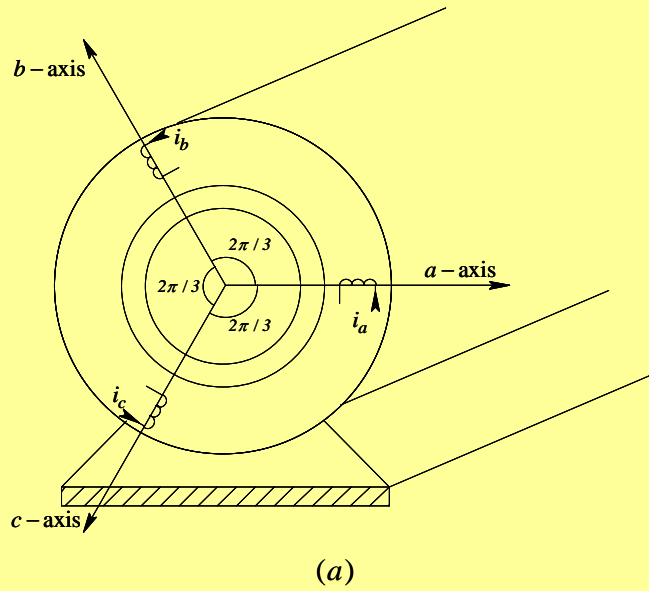


# PMAC Torque-Speed Characteristics

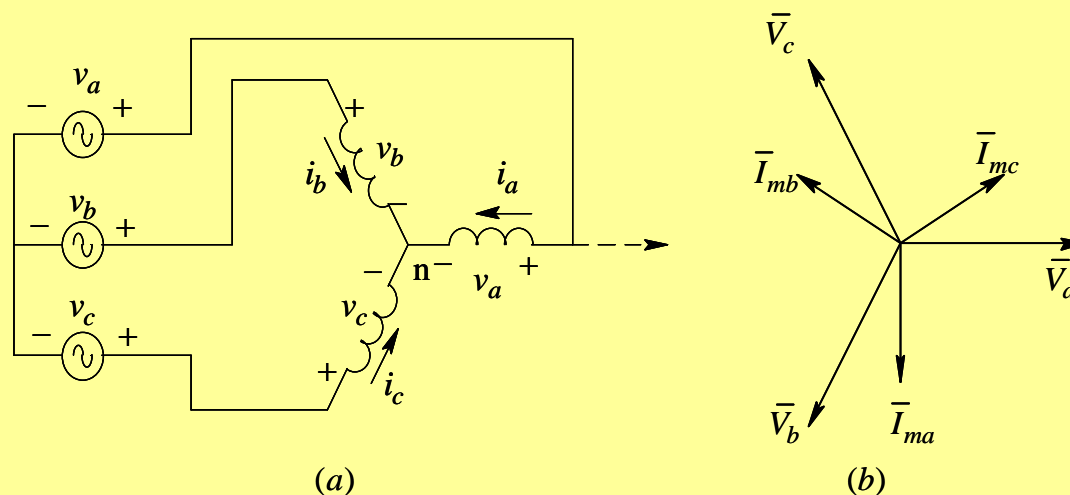




# Induction Machines



# Principles of Induction Motor Operation

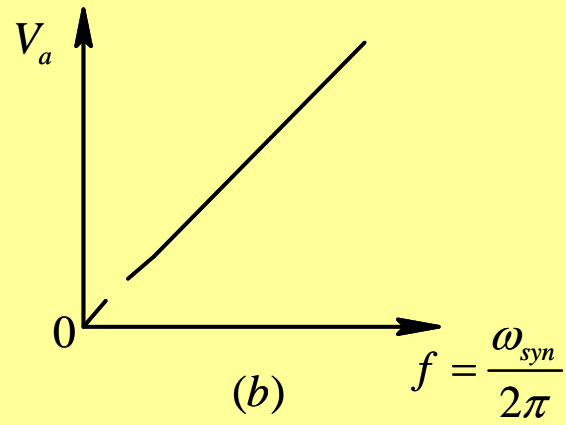
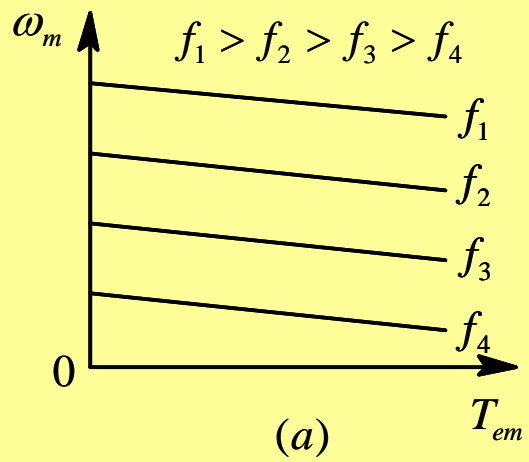


$$\bar{V}_a = V_{rms} \angle 0^\circ, \quad \bar{V}_b = V_{rms} \angle -120^\circ, \quad \text{and} \quad \bar{V}_c = V_{rms} \angle -240^\circ$$

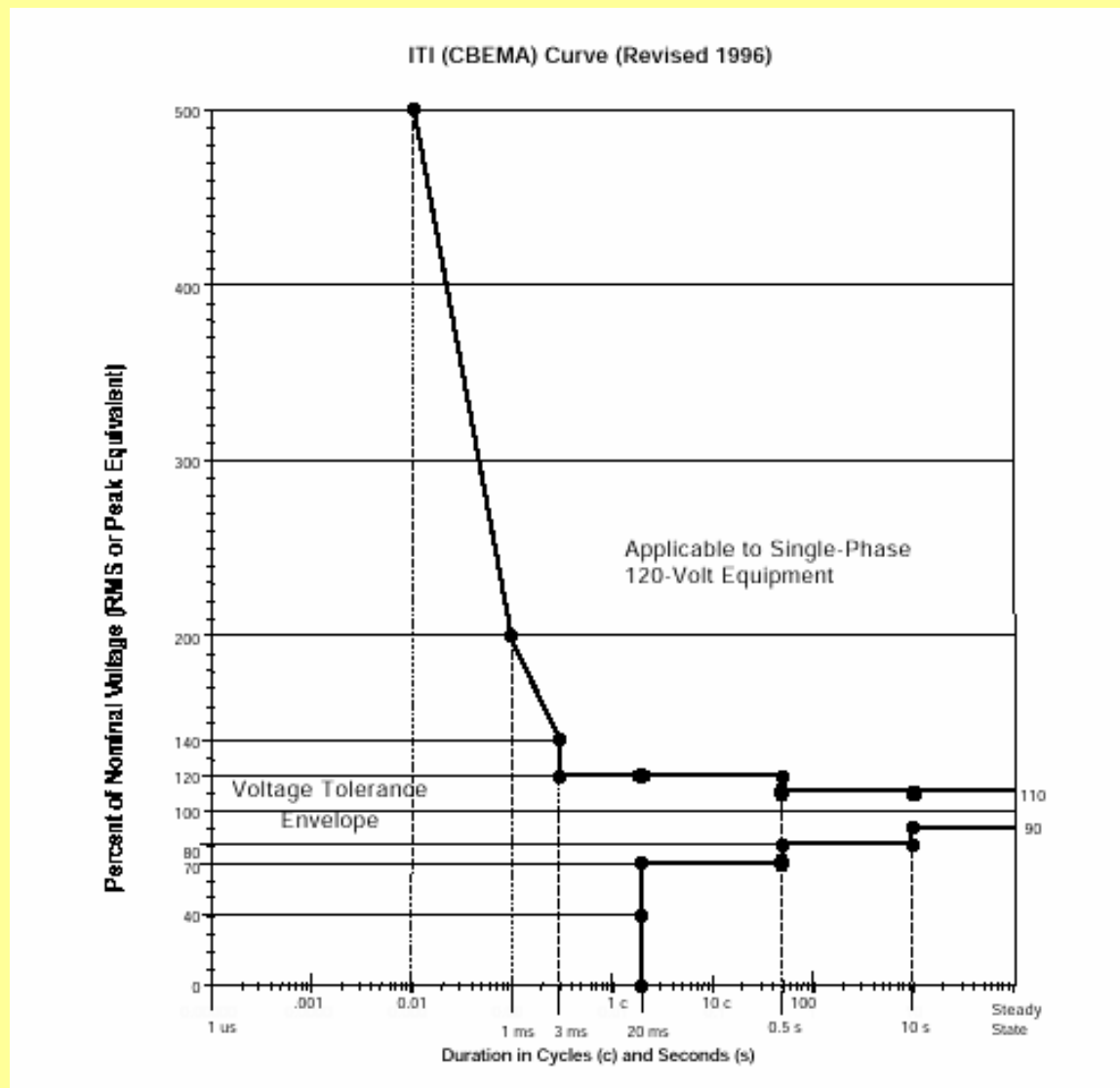
$$\bar{I}_{ma} = I_m \angle -90^\circ, \quad \bar{I}_{mb} = I_m \angle -210^\circ, \quad \text{and} \quad \bar{I}_{mc} = I_m \angle -330^\circ$$

$$\omega_{syn} = 2\pi f \qquad \omega_{syn} = \frac{2\pi f}{p/2} \quad \text{for a } p\text{-pole machine}$$

$$\text{slip speed} \quad \omega_{slip} = \omega_{syn} - \omega_m \qquad \text{slip frequency} \quad f_{slip} = \frac{\omega_{slip}}{\omega_{syn}} f$$

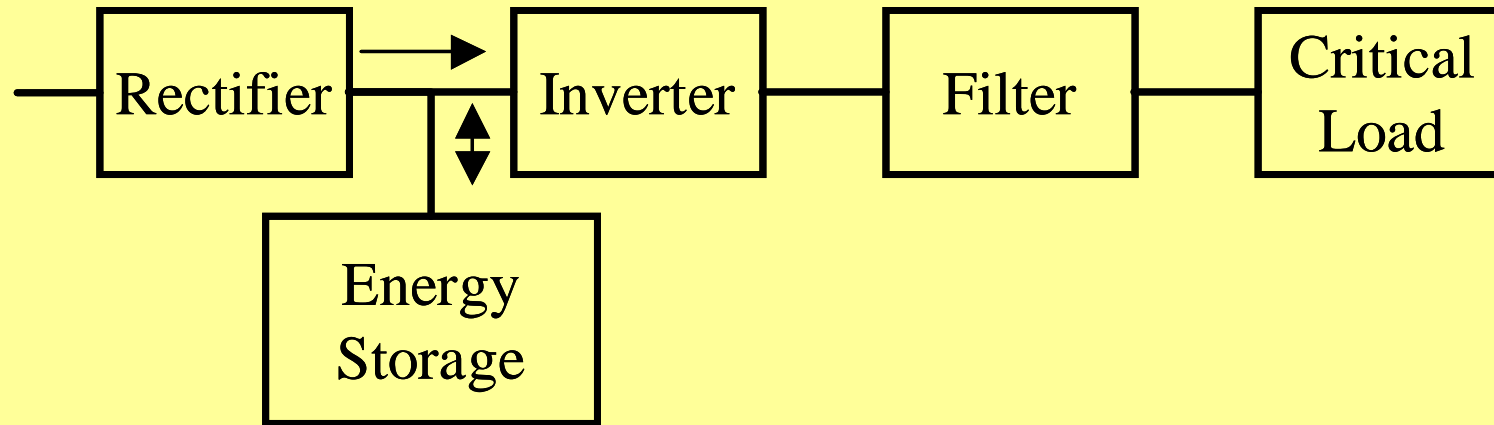


# UNINTERRUPTIBLE POWER SUPPLIES (UPS)

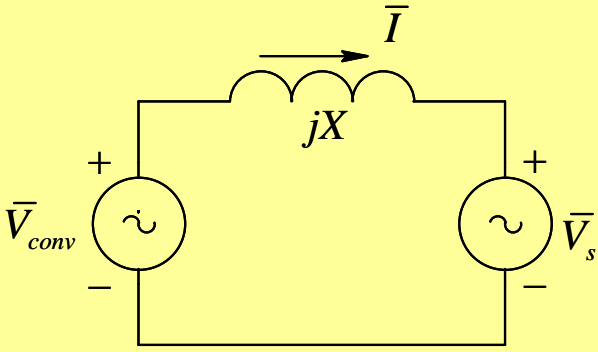
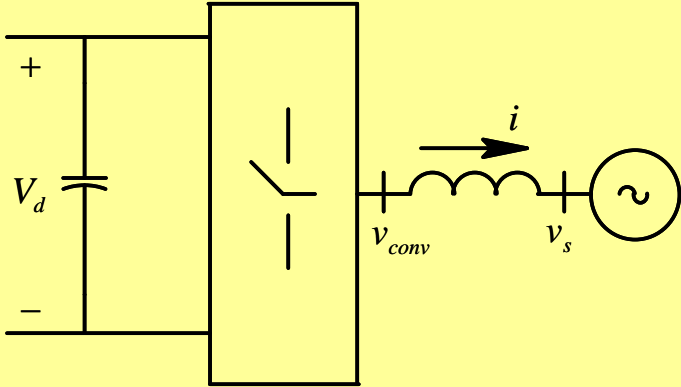


CBEMA Curve

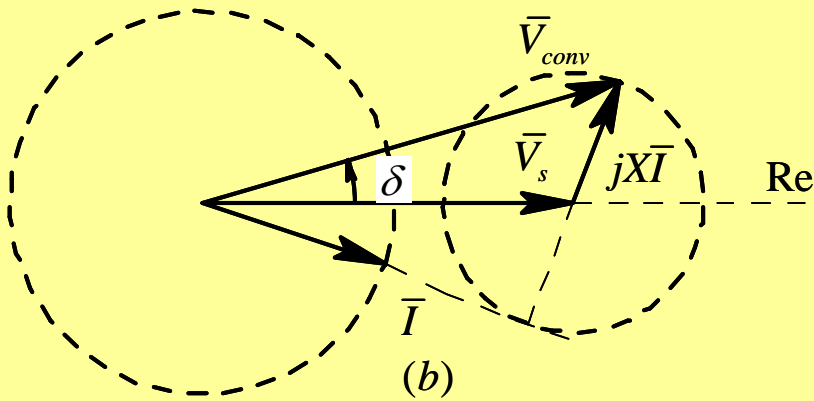
# UNINTERRUPTIBLE POWER SUPPLIES (UPS)



# UTILITY APPLICATIONS OF SWITCH-MODE POWER ELECTRONICS



(a)



(b)

# Summary

- Converter Voltage and Current Ratings in
  - Electric Drives
  - UPS
  - Utility Applications